

1.1.4, 1.6.1, 1.6.2, 1.6.3

Exercise 1.1.4. ^(a) Consider the vector space discussed in Exercise 1.1.1. Show that the elements $(1, 1, 0)$, $(1, 0, 1)$, and $(3, 2, 1)$ are linearly dependent. [Assume that one of them is a linear combination of the other two, and find the (nontrivial) coefficients of the expansion.] Show likewise that $(1, 1, 0)$, $(1, 0, 1)$, and $(0, 1, 1)$ are LI. ^(b)

(a) $\alpha \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \beta \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + \gamma \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = 0 \Rightarrow \alpha + \beta + 3\gamma = 0$

$\alpha + \beta + 2\gamma = 0 \Rightarrow \alpha = -2\gamma$

$0\alpha + \beta + \gamma = 0 \Rightarrow \beta = -\gamma$

Given: Use row reduction (same result):

$$\begin{bmatrix} 1 & 1 & 3 \\ 1 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} -1 & -1 & -3 \\ 1 & 0 & 2 \\ 0 & -1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 3 \\ 0 & -1 & -1 \\ 0 & 1 & 1 \end{bmatrix}$$

$\beta = -\gamma, \alpha = -2\gamma = 2\beta$) We can add a combination

Ex: $\beta = 1, \gamma = -1, \alpha = +2$ of these vectors to zero, so they are linearly dependent.

(b) $a \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + c \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \stackrel{?}{=} 0$ If so, then LD.

$a + b + 0c = 0 \rightarrow a = -b$ } $b = 0$

$a + 0b + c = 0 \rightarrow a = -c$ } $a = 0$

$0a + 0b + c = 0 \rightarrow c = 0$ }

The only way to add ^{a combination of} these three vectors to zero is to multiply them all by zero: TRIVIAL solution.

Therefore, these are linearly INDEPENDENT: LI ✓

Exercise 1.6.1. An operator Ω is given by the matrix

$$\begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\Omega|1\rangle = |2\rangle \quad \Omega|2\rangle = |3\rangle$$

$$\Omega|3\rangle = |1\rangle$$

What is its action? What is the axis of rotation? Rotation of 120° around $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ axis.
Check by operating on $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ - should produce NO CHANGE.

$\Omega|1\rangle = |2\rangle$: Ω operates on \hat{x} and rotates it into \hat{y}

$\Omega|2\rangle = |3\rangle$: Ω rotates \hat{y} into \hat{z}

$\Omega|3\rangle = |1\rangle$: Ω rotates \hat{z} into \hat{x}

Check: $\begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ ✓ Ω doesn't change $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ axis.

Exercise 1.6.2.* Given Ω and A are Hermitian what can you say about
(i) ΩA ; (ii) $\Omega A + A \Omega$; (iii) $[\Omega, A]$; and (iv) $i[\Omega, A]$?

Exercise 1.6.3.* Show that a product of unitary operators is unitary.

Ω^\dagger is the transpose conjugate of $\Omega = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$

$$\Omega^\dagger = \begin{bmatrix} a^* & d^* & g^* \\ b^* & e^* & h^* \\ c^* & f^* & i^* \end{bmatrix} \quad \text{If } \Omega = \Omega^\dagger \text{ then } \Omega \text{ is } \underline{\text{HERMITIAN}}$$

1.6.2 $\Omega = \Omega^\dagger$ and $A = A^\dagger$. (i) $(\Omega A)^\dagger = A^\dagger \Omega^\dagger$ (see eqn 1.6.16)
 $= A \Omega$

So (ΩA) is NOT Hermitian unless $(\Omega A) = (A \Omega)$,
that is, unless Ω and A commute.

($\mathcal{R} = \mathcal{R}^\dagger$ and $\Lambda = \Lambda^\dagger$ in this problem: Hermitian operators)

$$\begin{aligned} \text{A.6.2 (ii)} \quad (\mathcal{R}\Lambda + \Lambda\mathcal{R})^\dagger &= (\mathcal{R}\Lambda)^\dagger + (\Lambda\mathcal{R})^\dagger \\ &= \Lambda^\dagger\mathcal{R}^\dagger + \mathcal{R}^\dagger\Lambda^\dagger \\ &= \Lambda\mathcal{R} + \mathcal{R}\Lambda = \mathcal{R}\Lambda + \Lambda\mathcal{R} \end{aligned}$$

Therefore $(\mathcal{R}\Lambda + \Lambda\mathcal{R})$ is Hermitian.

(iii) $[\mathcal{R}, \Lambda]$ is defined as $\mathcal{R}\Lambda - \Lambda\mathcal{R} =$ COMMUTATOR of \mathcal{R} & Λ
(p. 22-23)

$$\begin{aligned} ([\mathcal{R}, \Lambda])^\dagger &= (\mathcal{R}\Lambda - \Lambda\mathcal{R})^\dagger = (\mathcal{R}\Lambda)^\dagger - (\Lambda\mathcal{R})^\dagger \\ &= \Lambda^\dagger\mathcal{R}^\dagger - \mathcal{R}^\dagger\Lambda^\dagger \\ &= \Lambda\mathcal{R} - \mathcal{R}\Lambda = -(\mathcal{R}\Lambda - \Lambda\mathcal{R}) \\ &= -[\mathcal{R}, \Lambda] \end{aligned}$$

Therefore $[\mathcal{R}, \Lambda]$ is ANTIHERMITIAN.

(iv) $i[\mathcal{R}, \Lambda] = i(\mathcal{R}\Lambda - \Lambda\mathcal{R}) = i(\mathcal{R}^\dagger\Lambda^\dagger - \Lambda^\dagger\mathcal{R}^\dagger)$ (not necessary...)

$$(i[\mathcal{R}, \Lambda])^\dagger = -i([\mathcal{R}, \Lambda])^\dagger = -i(-[\mathcal{R}, \Lambda]) = +i[\mathcal{R}, \Lambda]$$

Therefore, $i[\mathcal{R}, \Lambda]$ is HERMITIAN.

A.6.3 Let U and V be unitary: $U^\dagger U = I$, $V^\dagger V = I$.

$$\begin{aligned} \text{Then } (UV)^\dagger (UV) &= (V^\dagger U^\dagger)(UV) \quad (\text{eq. 1.6.16}) \\ &= V^\dagger (U^\dagger U) V \\ &= V^\dagger I V = V^\dagger V = I \end{aligned}$$

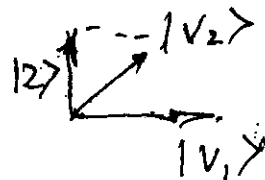
Therefore, the PRODUCT of unitary operators is also UNITARY.

Theorem 5 (Gram-Schmidt Theorem). Given n vectors $|V_1\rangle, |V_2\rangle, \dots, |V_n\rangle$ that are LI, we can get, by forming linear combinations, n orthonormal vectors, $|1\rangle, |2\rangle, \dots, |i\rangle, \dots, |n\rangle$.

Proof. Let us first construct n mutually orthogonal vectors. Let

$$|1'\rangle = |V_1\rangle$$

$$|2'\rangle = |V_2\rangle - \frac{|1'\rangle \langle 1' | V_2 \rangle}{\langle 1' | 1' \rangle}$$



Exercise 1.3.2. Consider the vectors

$$|V_1\rangle \leftrightarrow \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}, \quad |V_2\rangle \leftrightarrow \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \quad |V_3\rangle \leftrightarrow \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix}$$

Use the Gram-Schmidt procedure to get the following orthonormal basis:

$$|1\rangle \leftrightarrow \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad |2\rangle \leftrightarrow \begin{bmatrix} 0 \\ 1/5^{1/2} \\ 2/5^{1/2} \end{bmatrix}, \quad |3\rangle \leftrightarrow \begin{bmatrix} 0 \\ -2/5^{1/2} \\ 1/5^{1/2} \end{bmatrix}$$

Is this the only orthonormal basis you can get in this case? (What if you change the sign of the components of $|1\rangle$?)

$$|1\rangle = \frac{|V_1\rangle}{|V_1|} = \frac{\begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}}{3} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ is normal.}$$

Orthogonal (not necessarily normal) $|2'\rangle$ can be constructed by subtracting $\frac{\langle 1 | V_2 \rangle}{\langle 1 | 1 \rangle} |1\rangle$. The part of $|V_2\rangle$ parallel to $|1\rangle$ is

dot product $\langle 1 | V_2 \rangle = [1 \ 0 \ 0] \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = 0$. Great, $|V_2\rangle$ is already perpendicular to $|V_1\rangle$

$$\text{So } |2\rangle = \frac{|V_2\rangle}{|V_2|} = \frac{\begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}}{\sqrt{0+1+2^2}} = \frac{\begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}}{\sqrt{5}} = \begin{bmatrix} 0 \\ 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix}$$

To construct $|3'\rangle$ orthogonal to $|1\rangle$ and $|2\rangle$
 (or $|V_1\rangle$ and $|V_2\rangle$ in this case)

we need to subtract out the parallel components

$\langle 1 | V_3 \rangle$ and $\langle V_2 | V_3 \rangle$ (I'll use $|1\rangle$ since it's simpler than $|V_1\rangle$ and $|V_2\rangle$ since it's simpler than $|2\rangle$)

$$\langle 1 | V_3 \rangle = [1 \ 0 \ 0] \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix} = 0$$

(I'll use $|1\rangle$ since it's simpler than $|V_1\rangle$ and $|V_2\rangle$ since it's simpler than $|2\rangle$)

$|V_3\rangle$ is already orthogonal to $|V_1\rangle$ - great.

$$\langle V_2 | V_3 \rangle = [0 \ 1 \ 2] \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix} = 0 + 2 + 10 = 12$$

$$|3'\rangle = |V_3\rangle - \frac{\langle 2' | V_3 \rangle}{\langle 2' | 2' \rangle} |2'\rangle \quad \text{where } |2'\rangle = |V_2\rangle \text{ in this case}$$

$$\frac{\langle 2' | V_3 \rangle}{\langle 2' | 2' \rangle} = \frac{|V_2\rangle \langle V_2 | V_3 \rangle}{|V_2\rangle^2} = \frac{12 |V_2\rangle}{5}$$

$$|3'\rangle = \begin{bmatrix} 0 \\ 2 \\ 5 \end{bmatrix} - \frac{12}{5} \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 0 \\ 10 \\ 25 \end{bmatrix} - \frac{1}{5} \begin{bmatrix} 0 \\ 12 \\ 24 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix}$$

$$|3'\rangle = \sqrt{\langle 3' | 3' \rangle} = \sqrt{0 + 2^2 + 1} \cdot \frac{1}{\sqrt{5}} = \frac{\sqrt{5}}{5} = \frac{1}{\sqrt{5}}$$

$$|3\rangle = \frac{|3'\rangle}{|3'\rangle} = \begin{bmatrix} 0 \\ -2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix}$$

QM 1b Physical Systems HW Thus.5. April 2007

Math review II: Ch.1.7 - 1.10

Do 1.8.1 (p.45), 1.8.3, 1.8.5, 1.9.2 (p.60), 1.10.1, 1.10.2

Exercise 1.8.1. (a) Find the eigenvalues and normalized eigenvectors of the matrix

Find roots of

$$\det(\Omega - \omega I) = 0$$

$$\Omega = \begin{bmatrix} 1 & 3 & 1 \\ 0 & 2 & 0 \\ 0 & 1 & 4 \end{bmatrix}$$

$$(\Omega - \omega I) = \begin{bmatrix} 1-\omega & 3 & 1 \\ 0 & 2-\omega & 0 \\ 0 & 1 & 4-\omega \end{bmatrix}$$

(b) Is the matrix Hermitian? Are the eigenvectors orthogonal?

$$\det(\Omega - \omega I) = (1-\omega)[(2-\omega)(4-\omega) - 0] - 3(0-0) + 1(0-0) \\ = (1-\omega)(2-\omega)(4-\omega)$$

Eigenvalues are $\omega = 1, 2, 4$. Now find the eigenvectors $|\omega\rangle = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ corresponding to each.

$$(\Omega - \omega I)|\omega\rangle = 0 \rightarrow \begin{bmatrix} 1-\omega & 3 & 1 \\ 0 & 2-\omega & 0 \\ 0 & 1 & 4-\omega \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\omega=1: \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 & 3 & 1 \\ 0 & 2 & 0 \\ 0 & 1 & 3 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} \rightarrow \begin{matrix} 3b + c = 0 \\ 2b = 0 \\ b + 3c = 0 \end{matrix} \rightarrow \begin{matrix} b = c = 0 \\ a = \text{anything} \end{matrix}$$

normalized

So the eigenvector for $\omega=1$ is $|\omega=1\rangle \leftrightarrow \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ✓

$$\omega=2: \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 & 3 & 1 \\ 0 & 0 & 0 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} \rightarrow \begin{matrix} -a + 3b + c = 0 \\ b + 2c = 0 \end{matrix} \rightarrow \begin{matrix} a = -5c \\ b = -2c \end{matrix}$$

Let's choose $c=1$. Then one form of the $|\omega=2\rangle$

$$\text{eigenvector is } \begin{bmatrix} -5c \\ -2c \\ c \end{bmatrix} \rightarrow \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix} \quad \text{Norm} = \sqrt{5^2 + 2^2 + 1} \\ = \sqrt{25 + 4 + 1} = \sqrt{30}$$

$$\text{So } |\omega=2\rangle \leftrightarrow \frac{\begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix}}{\sqrt{30}} \quad \checkmark \quad (\text{normalized})$$

$$w=4: \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -3 & 3 & 1 \\ 0 & -2 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} \rightarrow \begin{array}{l} -3a + b + c = 0 \quad 3a = c \\ -2b = 0 \quad \rightarrow b = 0 \\ b = 0 \end{array}$$

Let's choose $a=1$. Then one form of the $|w=4\rangle$ eigen vector is $\begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$. Norm = $\sqrt{1^2 + 0^2 + 3^2} = \sqrt{1+9} = \sqrt{10}$

So $|w=4\rangle \leftrightarrow \frac{1}{\sqrt{10}} \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$ (normalized)

⑥ Is R Hermitian? Is $R^\dagger = R$?

$$R = \begin{bmatrix} 1 & 3 & 1 \\ 0 & 2 & 0 \\ 0 & 1 & 4 \end{bmatrix} \quad R^\dagger = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 2 & 1 \\ 1 & 0 & 4 \end{bmatrix}^* \neq R$$

NOT HERMITIAN.

Theorem: If Hermitian \rightarrow then \exists an orthogonal basis set of vectors.

Are the eigenvectors orthogonal? Since R is not Hermitian, we have to check.

$\langle v_i | v_j \rangle = \delta_{ij}$ for orthonormal vectors

$$\langle w=1 | w=4 \rangle = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix} \frac{1}{\sqrt{10}} = \frac{1}{\sqrt{10}} \neq 0$$

NOT ORTHOGONAL

Exercise 1.8.2.* Consider the matrix

$$\Omega = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad \Omega^\dagger = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}^* = \Omega$$

- (a) Is it Hermitian? YES: $\Omega = \Omega^\dagger$
 (b) Find its eigenvalues and eigenvectors.
 (c) Verify that $U^\dagger \Omega U$ is diagonal, U being the matrix of eigenvectors of Ω .

(b) Eigenvalues w solve $\det(\Omega - Iw) = 0$

$$\det \begin{bmatrix} 0-w & 0 & 1 \\ 0 & 0-w & 0 \\ 1 & 0 & 0-w \end{bmatrix} = \begin{bmatrix} -w & 0 & 1 \\ 0 & -w & 0 \\ 1 & 0 & -w \end{bmatrix} = \begin{matrix} -w(w^2-0) \\ -0 \\ +1(0+w) \end{matrix}$$

$$0 = -w^3 + w = -w(w^2 - 1) = -w(w+1)(w-1)$$

Eigen values $w = 0, 1, -1$

Eigenvectors $|w\rangle = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ satisfy $(\Omega - wI)|w\rangle = 0$

$$\begin{bmatrix} -w & 0 & 1 \\ 0 & -w & 0 \\ 1 & 0 & -w \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$w=0: \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow \begin{matrix} c=0 \\ b = \text{anything} \\ a=0 \end{matrix}$$

$$|w=0\rangle = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$w=1: \begin{bmatrix} -1 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \rightarrow \begin{matrix} a=c \\ b=0 \\ a=0 \end{matrix} \rightarrow |w=1\rangle = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \frac{1}{\sqrt{2}}$$

Exercise 1.8.3.* Consider the Hermitian matrix

$$\Omega = \frac{1}{2} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & -1 \\ 0 & -1 & 3 \end{bmatrix}$$

(a) Show that $\omega_1 = \omega_2 = 1$; $\omega_3 = 2$.

(b) Show that $|\omega = 2\rangle$ is any vector of the form

$$\frac{1}{(2a^2)^{1/2}} \begin{bmatrix} 0 \\ a \\ -a \end{bmatrix}$$

(c) Show that the $\omega = 1$ eigenspace contains all vectors of the form

$$\frac{1}{(b^2 + 2c^2)^{1/2}} \begin{bmatrix} b \\ c \\ c \end{bmatrix}$$

either by feeding $\omega = 1$ into the equations or by requiring that the $\omega = 1$ eigenspace be orthogonal to $|\omega = 2\rangle$.

(a) Eigenvalues solve $\det(\Omega - I\omega) = 0 = \begin{vmatrix} 1-\omega & 0 & 0 \\ 0 & \frac{3}{2}-\omega & -\frac{1}{2} \\ 0 & -\frac{1}{2} & \frac{3}{2}-\omega \end{vmatrix}$

$$0 = (1-\omega) \left[\left(\frac{3}{2}-\omega\right) \left(\frac{3}{2}-\omega\right) - \frac{1}{4} \right]$$

$$= (1-\omega) \left[\frac{9}{4} - \frac{1}{4} - 3\omega + \omega^2 \right] = (1-\omega)(\omega^2 - 3\omega + 2)$$

$$0 = (1-\omega)(\omega-1)(\omega-2)$$

$\rightarrow \omega = 1, 1, 2$ (degenerate)

(b) Eigen vectors $|\omega\rangle = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ satisfy $(\Omega - \omega I)|\omega\rangle = 0$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1-\omega & 0 & 0 \\ 0 & \frac{3}{2}-\omega & -\frac{1}{2} \\ 0 & -\frac{1}{2} & \frac{3}{2}-\omega \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

$\omega = 2$, $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -\frac{1}{2} & -\frac{1}{2} \\ 0 & -\frac{1}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} \rightarrow a = 0, b = -c \rightarrow |\omega = 2\rangle = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$

or any vector of the form $|\omega = 2\rangle = \frac{1}{\sqrt{2a^2}} \begin{bmatrix} 0 \\ a \\ -a \end{bmatrix}$

(a)

$$w=1: \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \frac{1}{2} & -\frac{1}{2} \\ 0 & -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} b \\ c \\ d \end{bmatrix} \rightarrow \begin{array}{l} b = \text{anything} \\ c = d \end{array}$$

$$|w=1\rangle = \frac{1}{\sqrt{b^2 + c^2 + c^2}} \begin{bmatrix} b \\ c \\ c \end{bmatrix} \quad \checkmark$$

Exercise 1.9.2.* If H is a Hermitian operator, show that $U = e^{iH}$ is unitary. (Notice the analogy with c numbers: if θ is real, $u = e^{i\theta}$ is a number of unit modulus.)

$$U = e^{iH} \equiv \sum_{n=0}^{\infty} \frac{(iH)^n}{n!} \quad (\text{where } (iH)^0 = I)$$

$$H^\dagger = H$$

$$U^\dagger = \left(\sum_{n=0}^{\infty} \frac{(iH)^n}{n!} \right)^\dagger = \sum_{n=0}^{\infty} \left[\frac{(iH)^n}{n!} \right]^\dagger = \sum_{n=0}^{\infty} \frac{(-iH)^n}{n!} = \sum_{n=0}^{\infty} \frac{(-iH)^n}{n!} = e^{-iH}$$

$$\text{So } UU^\dagger = e^{iH} e^{-iH} = e^0 = I \quad \checkmark$$

Exercise 1.10.1.* Show that $\delta(ax) = \delta(x)/|a|$. [Consider $\int \delta(ax) f(x) dx$. Remember that $\delta(x) = \delta(-x)$.]

$$\int_{-\infty}^{\infty} \delta(ax) f(x) dx = \int_{-\infty}^{\infty} \delta(|a|x) f(x) dx, \quad \text{Let } y = |a|x, \quad dy = |a| dx$$

$$\text{Then } \int_{-\infty}^{\infty} \delta(ax) f(x) dx = \int_{-\infty}^{\infty} \delta(y) f\left(\frac{y}{|a|}\right) \frac{dy}{|a|} = \frac{1}{|a|} f\left(\frac{y}{|a|}\right) \Big|_{y=0} = \frac{1}{|a|} f(0)$$

$$= \frac{1}{|a|} \int_{-\infty}^{\infty} \delta(x) f(x) dx = \int_{-\infty}^{\infty} \left[\frac{1}{|a|} \delta(x) \right] f(x) dx \rightarrow \delta(ax) = \frac{1}{|a|} \delta(x) \quad \checkmark$$

Exercise 1.10.2.* Show that

$$\delta(f(x)) = \sum_i \frac{\delta(x - x_i)}{|df/dx_i|} \quad \text{is nonzero only in the infinitesimal region around each } x_i.$$

where x_i are the zeros of $f(x)$. Hint: Where does $\delta(f(x))$ blow up? Expand $f(x)$ near such points in a Taylor series, keeping the first nonzero term.

$$\text{Near } x_i, \quad f(x) \approx f(x_i) + \frac{df}{dx} \Big|_{x_i} (x - x_i) = 0 + \frac{df}{dx} \Big|_{x_i} (x - x_i) = \frac{df}{dx} (x - x_i)$$

Use 1.10.1:

$$\text{near } x_i, \quad \delta(f(x)) = \frac{\delta(x - x_i)}{|df/dx_i|}. \quad \text{The total } \delta(f(x)) = \sum_i \frac{\delta(x - x_i)}{|df/dx_i|}$$

Recall $\delta(x - x_i) = 0$ if $x_i \neq x$. So the i th term won't interfere with the spike at any other x_j .

Ex 8.5 Consider the matrix
p.46

$$R = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

$$R = \begin{bmatrix} \frac{1}{2}(e^{i\theta} + e^{-i\theta}) & \frac{1}{2i}(e^{i\theta} - e^{-i\theta}) \\ -\frac{1}{2i}(e^{i\theta} - e^{-i\theta}) & \frac{1}{2}(e^{i\theta} + e^{-i\theta}) \end{bmatrix}$$

(a) Show that R is unitary. $U^\dagger U = I$

$$R^\dagger R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} \cos^2 \theta + \sin^2 \theta & \cos \theta \sin \theta - \sin \theta \cos \theta \\ \sin \theta \cos \theta - \cos \theta \sin \theta & \sin^2 \theta + \cos^2 \theta \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

(b) Show that its eigenvalues are $e^{i\theta}$ and $e^{-i\theta}$

Eigenvalues solve $\det(R - I\omega) = 0$ - $\begin{vmatrix} \frac{1}{2}(e^{i\theta} + e^{-i\theta}) - \omega & \frac{1}{2i}(e^{i\theta} - e^{-i\theta}) \\ \frac{1}{2i}(e^{-i\theta} - e^{i\theta}) & \frac{1}{2}(e^{i\theta} + e^{-i\theta}) - \omega \end{vmatrix}$

$$0 = \left(\frac{1}{2}(e^{i\theta} + e^{-i\theta}) - \omega \right) \left[\frac{1}{2}(e^{i\theta} + e^{-i\theta}) - \omega \right] - \left(\frac{1}{2i}(e^{i\theta} - e^{-i\theta}) \right) \left(\frac{1}{2i}(e^{-i\theta} - e^{i\theta}) \right)$$

$$= \cos^2 \theta + \omega^2 - (e^{i\theta} + e^{-i\theta})\omega + \sin^2 \theta$$

$$= \omega^2 - (e^{i\theta} + e^{-i\theta})\omega + 1$$

$$= (\omega - e^{i\theta})(\omega - e^{-i\theta}) \quad (\text{check})$$

$$= \omega^2 - \omega(e^{i\theta} + e^{-i\theta}) + e^0 \quad \checkmark$$

$$\rightarrow \omega = e^{i\theta}, e^{-i\theta} \quad \checkmark$$

(c) Find the corresponding eigenvectors. $|\omega\rangle = \begin{bmatrix} a \\ b \end{bmatrix}$ satisfy
 $0 = (R - \omega I)|\omega\rangle$

$$\omega = e^{i\theta}: \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{2}(e^{i\theta} + e^{-i\theta}) - e^{i\theta} & \frac{1}{2i}(e^{i\theta} - e^{-i\theta}) \\ \frac{1}{2i}(e^{-i\theta} - e^{i\theta}) & \frac{1}{2}(e^{i\theta} + e^{-i\theta}) - e^{i\theta} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} \frac{1}{2}(e^{-i\theta} - e^{i\theta}) & \frac{1}{2i}(e^{i\theta} - e^{-i\theta}) \\ \frac{1}{2i}(e^{-i\theta} - e^{i\theta}) & \frac{1}{2}(e^{-i\theta} - e^{i\theta}) \end{bmatrix}$$

$$\rightarrow (e^{-i\theta} - e^{i\theta})a = i(e^{i\theta} - e^{-i\theta})b \quad |\omega = e^{i\theta}\rangle = \begin{bmatrix} 1 \\ i \end{bmatrix} / \sqrt{2}$$

$$-a = ib$$

$$b = ia$$

© Is it easier to find eigenvectors with original form of R ?

$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} \cos\theta - w & \sin\theta \\ -\sin\theta & \cos\theta - w \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

For $w = e^{i\theta} = \cos\theta + i\sin\theta$

$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} \cos\theta - (\cos\theta + i\sin\theta) & \sin\theta \\ -\sin\theta & \cos\theta - (\cos\theta + i\sin\theta) \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -i\sin\theta & \sin\theta \\ -\sin\theta & -i\sin\theta \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$\rightarrow -i\sin\theta a + b\sin\theta = 0 \rightarrow ia = b$ Same, and easy!

For $w = e^{-i\theta} = \cos\theta - i\sin\theta$, $\cos\theta - w = \cos\theta - (\cos\theta - i\sin\theta) = +i\sin\theta$

$$\begin{bmatrix} 0 \\ a \end{bmatrix} = \begin{bmatrix} i\sin\theta & \sin\theta \\ -\sin\theta & i\sin\theta \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} \rightarrow \begin{matrix} -ia\sin\theta = b\sin\theta \\ -ia = b \end{matrix}$$

$$|w = e^{-i\theta}\rangle = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

Show that these eigenvectors are orthogonal:

$$\langle w = e^{i\theta} | w = e^{-i\theta} \rangle = \frac{1}{2} [1 - i] \begin{bmatrix} 1 \\ i \end{bmatrix} = \frac{1}{2} (1 + i^2) = \frac{1}{2} (1 - 1) = 0$$

* take complex conjugate

YES - orthogonal

© Verify that $U^{\dagger} R U = (\text{diagonal matrix})$ where

$U = \text{matrix of eigenvectors} : U = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ i & -i \end{bmatrix}$ $U^{\dagger} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -i \\ 1 & i \end{bmatrix}$

$$R U = \frac{1}{\sqrt{2}} \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} 1 & 1 \\ i & -i \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} \cos\theta + i\sin\theta & \cos\theta - i\sin\theta \\ -\sin\theta + i\cos\theta & -\sin\theta - i\cos\theta \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} e^{i\theta} & e^{-i\theta} \\ i e^{i\theta} & -i e^{-i\theta} \end{bmatrix}$$

$$U^{\dagger} R U = \frac{1}{2} \begin{bmatrix} 1 & -i \\ 1 & i \end{bmatrix} \begin{bmatrix} e^{i\theta} & e^{-i\theta} \\ i e^{i\theta} & -i e^{-i\theta} \end{bmatrix} = \frac{1}{2} \begin{bmatrix} e^{i\theta} + e^{-i\theta} & e^{-i\theta} - e^{i\theta} \\ i e^{i\theta} - i e^{-i\theta} & e^{i\theta} + e^{-i\theta} \end{bmatrix} = \begin{bmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{bmatrix}$$

Sure enough, this diagonalizes R with w on diagonal.