## Our goals in our study of Rotations (which includes Chapter 7 - Rotational Motion and the associated lecture, lab, problem session, and problem set) are to be able to:

- 1. Compare and contrast rotational kinematics and dynamics quantities with their analogous translational (i.e. linear) counterparts: angular position  $\theta$  and position x; angular velocity  $\omega$  and velocity v; angular acceleration  $\alpha$  and acceleration a; torque  $\tau$  and force F; moment of inertia (i.e. rotational inertia) I and mass m; and Newton's Second Law for rotations  $\vec{\tau}_{net} = I \vec{\alpha}$  and Newton's Second Law for translations  $\vec{F}_{net} = m\vec{a}$ .
- 2. Recognize  $\vec{\theta}$ ,  $\vec{\omega}$ ,  $\vec{\alpha}$ , and  $\vec{\tau}$  are vector quantities, and use the clockwise is negative and counterclockwise is positive convention to add and subtract these vector quantities.
- 3. Relate  $\theta$ ,  $\omega$ ,  $\alpha$  and time t algebraically and graphically.
- 4. Relate  $\omega$  to tangential velocity  $v_t$  and  $\alpha$  to tangential acceleration  $a_t$ .
- 5. Relate  $\tau$  to F, the distance F is applied from the pivot (axis of rotation): r, and the angle (between the force and the radial line):  $\phi$ . Alternatively, relate  $\tau$  to r and the perpendicular component of the force:  $F_{\perp}$ , or to F and the moment (or lever) arm:  $r_{\perp}$ .
- 6. For point particles, relate I to m and r, or for extended bodies use a formula to relate I to the mass of the object and its size.
- 7. Use  $\vec{\tau}_{net} = I \vec{\alpha}$  to solve rotational dynamics problems.
- 8. Use the no-slipping constraints to relate the linear motion of an object to the rotational motion of the same (or another connected) object, and to solve dynamics problems involving translations and rotations.

## **Reading Assignment**

Ch. 7: Rotational Motion (skip pp. 210-212 and section 7.6)

## **Problem Set**

Student Workbook Ch. 7: 1, 2, 5, 6, 17, 21, 23, 24

Ch. 7 Problems: 44, 45, 4, 6, 10, 11, 12, 13, 49, 32, 33, 34, 37, 41 (see Fig. P7.63 for a similar situation), 59

A1: A string is wrapped around a uniform solid cylinder of radius *r*, as shown in the figure. The cylinder can rotate freely about its axis. The loose end of the string is attached to a block. The block and cylinder each have mass m. As the block descends, the rope unwinds without slipping.

- a) Show that the block accelerates downward at  $\frac{2}{3}g$ .
- b) Discuss what happens to the acceleration of the block if the radius of the pulley doubles but the masses remain the same.

